Satisfiability and Model Checking for the Logic of Sub-Intervals under the Homogeneity Assumption[*][†]

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— Abstract

In this paper, we investigate the finite satisfiability and model checking problems for the logic D of the sub-interval relation under the homogeneity assumption, that constrains a proposition letter to hold over an interval if and only if it holds over all its points. First, we prove that the satisfiability problem for D, over finite linear orders, is **PSPACE**-complete; then, we show that its model checking problem, over finite Kripke structures, is **PSPACE**-complete as well.

1   Introduction

For a long time, interval temporal logic (ITL) was considered as an attractive, but impractical, alternative to standard point-based ones. On the one hand, as pointed out, among others, by Kamp and Reyle [9], "truth, as it pertains to language in the way we use it, relates sentences not to instants but to temporal intervals", and thus ITL is a natural choice for a specification/representation language; on the other hand, the high undecidability of the satisfiability problem for the most well-known ITLs, such as Halpern and Shoham's HS [7] and Venema's CDT [18], prevented an extensive use of them (in fact, some very restricted variants of them have been successfully applied in formal verification and AI over the years).

The recent discovery of a significant number of expressive enough and computationally well-behaved ITLs changed the landscape a lot [6, 13]. Among them, the logic $A\overline{A}$ of temporal neighborhood [5] and the logic D of (temporal) sub-intervals [4] have a central position. In this paper, we focus on the latter one. D features one modality only, which corresponds to the Allen relation *during* [1]. Since any sub-interval can be defined as an initial sub-interval of an ending one, or, equivalently, as an ending sub-interval of an initial one, it is a (proper) fragment of the logic BE of Allen's relations *started-by* and *finished-by*. From a computational point of view, D is a real character: its satisfiability problem is **PSPACE**-complete over the class of dense linear orders [4, 16] (the problem is undecidable for BE [10]), it becomes undecidable when the logic is interpreted over the classes of finite and discrete linear orders [11], and it is still unknown over the class of all linear orders. As for its expressiveness, unlike $A\overline{A}$– which is expressively complete with respect to the two-variable fragment of first-order logic for binary relational structures over various linearly-ordered domains [5, 15] – three variables are needed to encode D in first-order logic (the two-variable property is a sufficient condition for decidability, but it is not a necessary one).

In this paper, we show that the decidability of the satisfiability problem for D over the class of finite linear orders can be recovered under the homogeneity assumption (such an assumption constrains a proposition letter to hold over an interval if and only if it holds over all its points). We first prove that the problem belongs to **PSPACE** by exploiting a suitable contraction method. In addition, we prove that the proposed satisfiability checking algorithm can be turned into a **PSPACE** model checking procedure for D formulas over finite Kripke structures (under the homogeneity assumption); **PSPACE**-hardness of both problems follows via a reduction from the language universality problem of nondeterministic finite-state automata. **PSPACE**-completeness of D model checking strongly contrasts with the case of BE, for which only a nonelementary model checking procedure is known [12] and an **EXPSPACE**-hardness result has been given [2].

The rest of the paper is organized as follows. In Section 2, we provide some background knowledge. Then, in Section 3, we prove the **PSPACE** membership of the satisfiability problem for D over finite linear orders (under the homogeneity assumption). Finally, in Section 4, we show that the model checking problem for D over finite Kripke structures (again, under the homogeneity assumption) is in **PSPACE** as well.

All the proofs – here omitted because of lack of space – can be found in [3].

2   The logic D of the sub-interval relation

Let $\mathbb{S} = \langle S, < \rangle$ be a linear order. An *interval* over $\mathbb{S}$ is an ordered pair $[x, y]$, where $x \leq y$. We denote the set of all intervals over $\mathbb{S}$ by $\mathbb{I}(\mathbb{S})$. We consider three possible *sub-interval relations*: (i) the *reflexive* sub-interval relation (denoted as $\sqsubseteq$), defined by $[x, y] \sqsubseteq [x', y']$ iff $x' \leq x$ and $y \leq y'$, (ii) the *proper (or irreflexive)* sub-interval relation (denoted as $\sqsubset$), defined by $[x, y] \sqsubset [x', y']$ iff $[x, y] \sqsubseteq [x', y']$ and $[x, y] \neq [x', y']$, and (iii) the *strict* sub-interval relation (denoted as $\sqsubset\!\!\!\cdot\,$), defined by $[x, y]\sqsubset\!\!\!\cdot\,[x', y']$ iff $x' < x$ and $y < y'$.

The three modal logics $D_\sqsubseteq$, $D_\sqsubset$, and $D_{\sqsubset\!\cdot}$ feature the same language, consisting of a set $\mathcal{AP}$ of proposition letters/variables, the logical connectives $\neg$ and $\vee$, and the modal operator $\langle D \rangle$. Formally, formulae are defined by the grammar: $\varphi ::= p \mid \neg\varphi \mid \varphi \vee \varphi \mid \langle D \rangle\varphi$, with $p \in \mathcal{AP}$. The other connectives, as well as the logical constants $\top$ (true) and $\bot$ (false), are defined as usual; moreover, the dual universal modal operator $[D]\varphi$ is defined as $\neg\langle D \rangle\neg\varphi$. The length of a formula φ, denoted as $|\varphi|$, is the number of sub-formulas of φ.

The semantics of $D_{\sqsubset\!\cdot}$, $D_\sqsubset$, and $D_\sqsubseteq$ only differ in the interpretation of the $\langle D \rangle$ operator.

For the sake of brevity, we use $\circ \in \{\sqsubset\!\!\cdot, \sqsubset, \sqsubseteq\}$ as a shorthand for any of the three sub-interval relations. The semantics of a sub-interval logic $D_\circ$ is defined in terms of *interval models* $\mathbf{M} = \langle \mathbb{I}(\mathbb{S}), \circ, \mathcal{V} \rangle$. The *valuation function* $\mathcal{V} : \mathcal{AP} \mapsto 2^{\mathbb{I}(\mathbb{S})}$ assigns to every proposition variable p the set of intervals $\mathcal{V}(p)$ over which p holds. The *satisfiability relation* $\models$ is defined as:

- for every proposition letter $p \in \mathcal{AP}$, $\mathbf{M}, [x, y] \models p$ iff $[x, y] \in \mathcal{V}(p)$;
- $\mathbf{M}, [x, y] \models \neg\psi$ iff $\mathbf{M}, [x, y] \not\models \psi$ (i.e., it is not true that $\mathbf{M}, [x, y] \models \psi$);
- $\mathbf{M}, [x, y] \models \psi_1 \vee \psi_2$ iff $\mathbf{M}, [x, y] \models \psi_1$ or $\mathbf{M}, [x, y] \models \psi_2$;
- $\mathbf{M}, [x, y] \models \langle D \rangle \psi$ iff there is an interval $[x', y'] \in \mathbb{I}(\mathbb{S})$ s.t. $[x', y'] \circ [x, y]$ and $\mathbf{M}, [x', y'] \models \psi$.

A $D_\circ$-formula is $D_\circ$-*satisfiable* if it holds over some interval of an interval model and it is $D_\circ$-*valid* if it holds over every interval of every interval model.

In this paper, we restrict our attention to the finite satisfiability problem, that is, satisfiability over the class of finite linear orders. The problem has been shown to be *undecidable* for $D_{\sqsubset\!\!\cdot}$ and $D_\sqsubset$ [11] and *decidable* for $D_\sqsubseteq$ [14]. In the following, we show that decidability can be recovered for $D_{\sqsubset\!\!\cdot}$ and $D_\sqsubset$ by restricting to the class of *homogeneous* interval models. We fully work out the case of $D_{\sqsubset\!\!\cdot}$ (for the sake of simplicity, we will write D for $D_{\sqsubset\!\!\cdot}$), and then we briefly explain how to adapt the proofs to $D_\sqsubset$.

▶ **Definition 1.** A model $\mathbf{M} = \langle \mathbb{I}(\mathbb{S}), \circ, \mathcal{V} \rangle$ is homogeneous if, for every interval $[x, y] \in \mathbb{I}(\mathbb{S})$ and every $p \in \mathcal{AP}$, it holds that $[x, y] \in \mathcal{V}(p)$ iff $[x', x'] \in \mathcal{V}(p)$ for every $x \le x' \le y$.

Hereafter, we will refer to the logic D interpreted over homogeneous models as $D|_{\mathcal{H}om}$.

2.1 A spatial representation of interval models

We now introduce some basic definitions and notation which will be extensively used in the following. Given a D-formula φ, we define the *closure of* φ, denoted by $\mathrm{CL}(\varphi)$, as the set of all sub-formulas ψ of φ and of their negations $\neg\psi$ (we identify $\neg\neg\psi$ with ψ).

▶ **Definition 2.** Given a D-formula φ, a φ-atom A is a subset of $\mathrm{CL}(\varphi)$ such that: (i) for every $\psi \in \mathrm{CL}(\varphi)$, $\psi \in A$ iff $\neg\psi \notin A$, and (ii) for every $\psi_1 \vee \psi_2 \in \mathrm{CL}(\varphi)$, $\psi_1 \vee \psi_2 \in A$ iff $\psi_1 \in A$ or $\psi_2 \in A$.

The idea underlying atoms is to enforce a "local" (or Boolean) form of consistency among the formulas it contains, that is, a φ-atom A is a *maximal, locally consistent subset* of $\mathrm{CL}(\varphi)$. As an example, $\neg(\psi_1 \vee \psi_2) \in A$ iff $\neg\psi_1 \in A$ and $\neg\psi_2 \in A$. However, note that the definition does not set any constraint on $\langle D \rangle \psi$ formulas, hence the word "local". We denote the set of all φ-atoms as $\mathcal{A}_\varphi$; its cardinality is clearly bounded by $2^{|\varphi|}$ (by point (i) of Definition 2). Atoms are connected by the following binary relation D_φ.

▶ **Definition 3.** Let D_φ be a binary relation over $\mathcal{A}_\varphi$ such that, for each pair of atoms $A, A' \in \mathcal{A}_\varphi$, $A \, D_\varphi \, A'$ holds iff both $\psi \in A'$ and $[D]\psi \in A'$ for each formula $[D]\psi \in A$.

Let A be a φ-atom. We denote by $\mathcal{R}eq_D(A)$ the set $\{\psi \in \mathrm{CL}(\varphi) : \langle D \rangle \psi \in A\}$ of "temporal requests" of A. In particular, if $\psi \notin \mathcal{R}eq_D(A)$, then $[D]\neg\psi \in A$ (by the definition of φ-atom). Moreover, we denote by REQ_φ the set of all arguments of $\langle D \rangle$-formulas in $\mathrm{CL}(\varphi)$, namely, $\mathrm{REQ}_\varphi = \{\psi : \langle D \rangle \psi \in \mathrm{CL}(\varphi)\}$. Finally, we denote by $\mathcal{O}bs_D(A)$ the set $\{\psi \in A : \psi \in \mathrm{REQ}_\varphi\}$ of observables of A. It is easy to prove by induction the next proposition, stating that, once the proposition letters of A and its temporal requests have been fixed, A gets unambiguously determined.

▶ **Proposition 4.** *For any* D*-formula φ, given a set $R \subseteq \mathrm{REQ}_\varphi$ and a set $P \subseteq \mathrm{CL}(\varphi) \cap \mathcal{AP}$, there exists a unique φ-atom A that satisfies $\mathcal{R}eq_D(A) = R$ and $A \cap \mathcal{AP} = P$.*
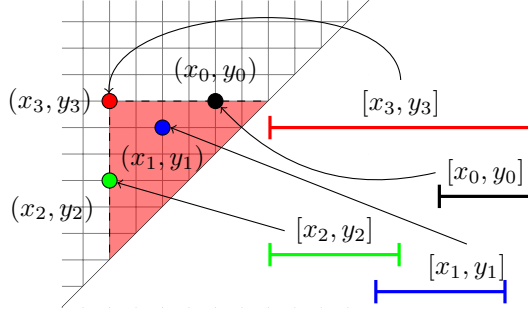
Figure 1 Correspondence between intervals and points of the compass structure.

We now provide a natural interpretation of D over grid-like structures, called *compass structures*, by exploiting the existence of a natural bijection between intervals $[x, y]$ and points (x, y), with $x \leq y$, of an $S \times S$ grid, where $\mathbb{S} = \langle S, < \rangle$ is a finite linear order. Such an interpretation was originally proposed by Venema in [17], and it can also be given for HS and all its (other) fragments.

As an example, Figure 1 shows four intervals $[x_0, y_0], \ldots, [x_3, y_3]$, respectively represented by the points in the grid $(x_0, y_0), \ldots, (x_3, y_3)$, such that: (i) $[x_0, y_0], [x_1, y_1], [x_2, y_2] \sqsubset [x_3, y_3]$, (ii) $[x_1, y_1] \sqsubset [x_3, y_3]$, and (iii) $[x_0, y_0], [x_2, y_2] \not\sqsubset [x_3, y_3]$. The red region highlighted in Figure 1 contains all and only the points (x, y) such that $[x, y] \sqsubset [x_3, y_3]$. Allen interval relation *contains* can thus be represented as a spatial relation between pairs of points. In the following, we make use of $\sqsubset$ also for relating points, i.e., given two points $(x, y), (x', y')$ of the grid, $(x', y') \sqsubset (x, y)$ iff $(x', y') \neq (x, y)$ and $x \leq x' \leq y' \leq y$. Compass structures, repeatedly exploited to establish the following complexity results, can be formally defined as follows.

▶ **Definition 5.** Given a finite linear order $\mathbb{S} = \langle S, < \rangle$ and a D-formula φ, a *compass φ-structure* is a pair $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$, where $\mathbb{P}_{\mathbb{S}}$ is the set of points of the form (x, y), with $x, y \in S$ and $x \leq y$, and $\mathcal{L}$ is a function that maps any point $(x, y) \in \mathbb{P}_{\mathbb{S}}$ to a φ-atom $\mathcal{L}(x, y)$ in such a way that for all pairs of points $(x, y) \neq (x', y') \in \mathbb{P}_{\mathbb{S}}$, if $x \leq x' \leq y' \leq y$, then $\mathcal{L}(x, y) \, D_\varphi \, \mathcal{L}(x', y')$ (*temporal consistency*).

Due to temporal consistency, the following important property holds in compass structures.

▶ **Lemma 6.** *Given a compass φ-structure $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$, for all pairs of points $(x', y'), (x, y) \in \mathbb{P}_{\mathbb{S}}$, if $(x', y') \sqsubset (x, y)$, then $\mathcal{R}eq_D(\mathcal{L}(x', y')) \subseteq \mathcal{R}eq_D(\mathcal{L}(x, y))$ and $\mathcal{O}bs_D(\mathcal{L}(x', y')) \subseteq \mathcal{R}eq_D(\mathcal{L}(x, y))$.*

Fulfilling compass structures are defined as follows.

▶ **Definition 7.** A compass φ-structure $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$ is said to be *fulfilling* if, for every point $(x, y) \in \mathbb{P}_{\mathbb{S}}$ and each formula $\psi \in \mathcal{R}eq_D(\mathcal{L}(x, y))$, there exists a point $(x', y') \sqsubset (x, y)$ in $\mathbb{P}_{\mathbb{S}}$ such that $\psi \in \mathcal{L}(x', y')$.

Note that if $\mathcal{G}$ is fulfilling, then $\mathcal{R}eq_D(\mathcal{L}(x, x)) = \emptyset$ for all points "on the diagonal" $(x, x) \in \mathbb{P}_{\mathbb{S}}$.

We say that a compass φ-structure $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$ *features* a formula ψ if there exists a point $(x, y) \in \mathbb{P}_{\mathbb{S}}$ such that $\psi \in \mathcal{L}(x, y)$. The following result holds.

▶ **Proposition 8.** *A D-formula φ is satisfiable iff there is a fulfilling compass φ-structure that features it.*

In a fulfilling compass φ-structure $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$, where $S = \{0, \ldots, t\}$, w.l.o.g., we will sometimes assume φ to be satisfied by the maximal interval $[0, t]$, that is, $\varphi \in \mathcal{L}(0, t)$.

The notion of homogeneous models directly transfers to compass structures.

▶ **Definition 9.** A compass φ-structure $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$ is *homogeneous* if, for every point $(x, y) \in \mathbb{P}_\mathbb{S}$ and each $p \in \mathcal{AP}$, we have that $p \in \mathcal{L}(x, y)$ iff $p \in \mathcal{L}(x', x')$ for all $x \leq x' \leq y$.

Proposition 8 can be tailored to homogeneous compass structures as follows.

▶ **Proposition 10.** *A* $\mathrm{D}|_{\mathcal{H}om}$*-formula* φ *is satisfiable iff there is a fulfilling homogeneous compass* φ*-structure that features it.*

3 Satisfiability of $\mathrm{D}|_{\mathcal{H}om}$ over finite linear orders

In this section, we devise a satisfiability checking procedure for $\mathrm{D}|_{\mathcal{H}om}$-formulas over finite linear orders, which will also allow us to easily derive a model checking algorithm for $\mathrm{D}|_{\mathcal{H}om}$ over finite Kripke structures. To start with, we show that there is a ternary relation between φ-atoms, that we denote by $=^{D_\varphi}\!\!\!\rightarrow$, such that if it holds among all atoms in consecutive positions of a compass φ-structure, then the structure is fulfilling. Hence, we may say that $=^{D_\varphi}\!\!\!\rightarrow$ is the rule for labeling fulfilling compasses. Next, we introduce an equivalence relation $\sim$ between *rows* of a compass φ-structure. Since it has finite index – exponentially bounded by $|\varphi|$ – and it preserves fulfillment of compasses, it is intuitively possible to "contract" the structures when we can find two related rows. Moreover, any contraction done according to $\sim$ keeps the same atoms (only the number of their occurrences may vary), and thus if a compass features φ before the contraction, then φ is still featured after it. This fact is exploited to build a satisfiability algorithm for $\mathrm{D}|_{\mathcal{H}om}$-formulas which makes use of *polynomial working space* only, because (i) it only needs to keep track of two rows of a compass at a time, (ii) all rows satisfy some nice properties that make it possible to succinctly encode them, and (iii) compass contractions are implicitly performed by means of a reachability check in a suitable graph, whose nodes are the equivalence classes of $\sim$.

Let us now introduce the aforementioned ternary relation $=^{D_\varphi}\!\!\!\rightarrow$ among atoms.

▶ **Definition 11.** Given three φ-atoms A_1, A_2 and A_3, we say that A_3 is D_φ-generated by A_1, A_2 (written $A_1 A_2 =^{D_\varphi}\!\!\!\rightarrow A_3$) if: (i) $A_3 \cap \mathcal{AP} = A_1 \cap A_2 \cap \mathcal{AP}$ and (ii) $\mathcal{R}eq_D(A_3) = \mathcal{R}eq_D(A_1) \cup \mathcal{R}eq_D(A_2) \cup \mathcal{O}bs_D(A_1) \cup \mathcal{O}bs_D(A_2)$.

It is immediate to check that $A_1 A_2 =^{D_\varphi}\!\!\!\rightarrow A_3$ iff $A_2 A_1 =^{D_\varphi}\!\!\!\rightarrow A_3$, that is, the order of the first two components in the ternary relation is irrelevant. The next result, following from Proposition 4, proves that $=^{D_\varphi}\!\!\!\rightarrow$ expresses a *functional dependency* on φ-atoms.

▶ **Lemma 12.** *Given two* φ*-atoms* $A_1, A_2 \in \mathcal{A}_\varphi$*, there exists exactly one* φ*-atom* $A_3 \in \mathcal{A}_\varphi$ *such that* $A_1 A_2 =^{D_\varphi}\!\!\!\rightarrow A_3$.

Definition 11 and Lemma 12 can be exploited to label a homogeneous compass φ-structure $\mathcal{G}$, namely, to determine the φ-atoms labeling all the points (x, y) of $\mathcal{G}$, starting from the ones on the diagonal. The idea is the following: if two φ-atoms A_1 and A_2 label respectively the greatest proper prefix $[x, y - 1]$, that is, the point $(x, y - 1)$, and the greatest proper suffix $[x + 1, y]$, that is, $(x + 1, y)$, of the same interval $[x, y]$, then the atom A_3 labeling $[x, y]$ is unique, and it is precisely the one satisfying $A_1 A_2 =^{D_\varphi}\!\!\!\rightarrow A_3$ (see Figure 2). The next lemma proves that this is the general rule for labeling fulfilling homogeneous compasses.

▶ **Lemma 13.** *Let* $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$*.* $\mathcal{G}$ *is a fulfilling homogeneous compass* φ*-structure iff, for every pair* $x, y \in S$*, we have: (i)* $\mathcal{L}(x, y - 1)\mathcal{L}(x + 1, y) =^{D_\varphi}\!\!\!\rightarrow \mathcal{L}(x, y)$ *if* $x < y$*, and (ii)* $\mathcal{R}eq_D(\mathcal{L}(x, y)) = \emptyset$ *if* $x = y$*.*
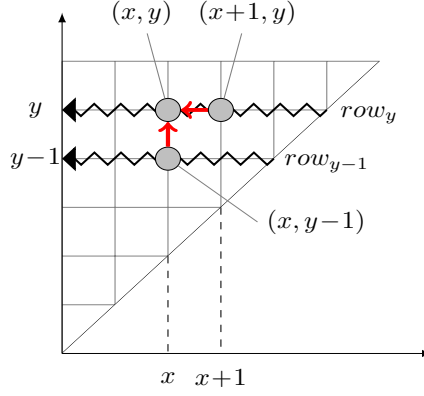
Figure 2 Rule for labeling homogeneous fulfilling compass φ-structures.

Now we introduce the concept of φ-row, which can be viewed as the ordered sequence of (the occurrences of) atoms labelling a row of a compass φ-structure. Given an atom $A \in \mathcal{A}_\varphi$, we call it *reflexive* if $A\ D_\varphi\ A$, *irreflexive* otherwise.

▶ **Definition 14.** A φ-row is a finite sequence of φ-atoms $row = A_0^{m_0} \cdots A_n^{m_n}$, where A^m stands for m repetitions of A, such that for each $0 \leq i \leq n$, we have that $m_i > 0$ – if $m_i > 1$, then A_i is reflexive – and for each $0 \leq j < i$, it holds that $A_i\ D_\varphi\ A_j$, $A_i \neq A_j$, and $(A_j \cap \mathcal{AP}) \supseteq (A_i \cap \mathcal{AP})$. Moreover, $\mathcal{R}eq_D(A_0) = \emptyset$.

The length of a φ-row $row = A_0^{m_0} \cdots A_n^{m_n}$ is defined as $|row| = \sum_{0 \leq i \leq n} m_i$, and for each $0 \leq j < |row|$, the j-th element, denoted by $row[j]$, is the j-th symbol in the word $A_0^{m_0} \cdots A_n^{m_n}$, e.g., $row[0] = A_0$, $row[m_0] = A_1$, ... We denote by $\mathcal{R}ows_\varphi$ the set of all possible φ-rows. This set may be infinite.

The number of distinct atoms in any φ-row is bounded. Since for each $0 \leq i \leq n$ and each $0 \leq j < i$, $A_i\ D_\varphi\ A_j$, it holds that $\mathcal{R}eq_D(A_j) \subseteq \mathcal{R}eq_D(A_i)$. Therefore, two monotonic sequences for every φ-row can be considered, one increasing, i.e., $\emptyset = \mathcal{R}eq_D(A_0) \subseteq \mathcal{R}eq_D(A_1) \subseteq \ldots \subseteq \mathcal{R}eq_D(A_n)$, and one decreasing, i.e., $(A_0 \cap \mathcal{AP}) \supseteq (A_1 \cap \mathcal{AP}) \supseteq \ldots \supseteq (A_n \cap \mathcal{AP})$. The number of distinct elements is bounded by $|\varphi|$ in the former sequence and by $|\varphi| + 1$ in the latter (as $|\operatorname{REQ}_\varphi| \leq |\varphi| - 1$ and $|\mathcal{AP}| \leq |\varphi|$–w.l.o.g., we can consider only the letters actually occurring in φ). Since, as already shown (Proposition 4), a set of requests and a set of proposition letters uniquely determine a φ-atom, any φ-row may feature at most $2|\varphi|$ distinct atoms, i.e., $n < 2|\varphi|$.

Given a homogeneous compass φ-structure $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$, for every $y \in S$, we define row_y as the word of φ-atoms $row_y = \mathcal{L}(y, y) \cdots \mathcal{L}(0, y)$, i.e., the sequence of atoms labeling points of $\mathcal{G}$ with the same y-coordinate, starting from the one on the diagonal inwards (see Figure 2).

▶ **Lemma 15.** *Let $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$ be a fulfilling homogeneous compass φ-structure. For every $y \in S$, row_y is a φ-row.*

We now define the *successor* relation between pairs of φ-rows, denoted as $=^{row_\varphi}\!\!\!\rightarrow$, which is basically a component-wise application of $=^{D_\varphi}\!\!\!\rightarrow$ over the elements of two φ-rows (remember that atoms on rows are collected from right to left).

▶ **Definition 16.** Given two φ-rows row and row', we say that row' is a *successor* of row, or $row =^{row_\varphi}\!\!\!\rightarrow row'$, if $|row'| = |row| + 1$, and for all $0 \leq i < |row|$, $row[i]row'[i] =^{D_\varphi}\!\!\!\rightarrow row'[i+1]$.
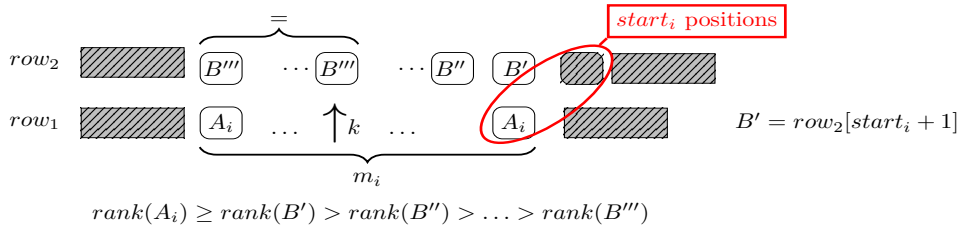
Figure 3 A graphical account of the proof of Lemma 18.

The next lemma states that consecutive rows in homogeneous fulfilling compass φ-structures respect the successor relation.

▶ **Lemma 17.** *Let $\mathcal{G} = (\mathbb{P}_{\mathbb{S}}, \mathcal{L})$, with $\mathcal{R}eq_D(\mathcal{L}(x,x)) = \emptyset$ for all $(x,x) \in \mathbb{P}_{\mathbb{S}}$. $\mathcal{G}$ is a fulfilling homogeneous compass φ-structure iff, for each $0 \leq y < |S| - 1$, $row_y \xrightarrow{=row_\varphi} row_{y+1}$.*

Given an atom $A \in \mathcal{A}_\varphi$, we define the *rank of A*, written $rank(A)$, as $|\mathrm{REQ}_\varphi| - |\mathcal{R}eq_D(A)|$. Clearly, $rank(A) < |\varphi|$. Whenever $A \, D_\varphi \, A'$, for some $A' \in \mathcal{A}_\varphi$, $\mathcal{R}eq_D(A') \subseteq \mathcal{R}eq_D(A)$, and hence $rank(A) \leq rank(A')$ and $|\mathcal{R}eq_D(A) \setminus \mathcal{R}eq_D(A')| \leq rank(A')$. We can see the *rank* of an atom as the "number of degrees of freedom" that it gives to the atoms that stay "above it". In particular, by definition, for every φ-row $row = A_0^{m_0} \cdots A_n^{m_n}$, we have $rank(A_0) \geq \ldots \geq rank(A_n)$. The next result uses the notion of rank to provide an insight on how consecutive φ-rows are connected (see Figure 3).

▶ **Lemma 18.** *Let row_1, row_2 be two φ-rows, with $row_1 = A_0^{m_0} \cdots A_n^{m_n}$ and $row_1 \xrightarrow{=row_\varphi} row_2$. For each $0 \leq i \leq n$, let $start_i = \sum_{0 \leq j < i} m_j$. If $m_i > rank(A_i)$, then there exists $start_i < k \leq start_i + m_i$ such that: (i) $row_2[k]$ is reflexive; (ii) $rank(row_2[j]) > rank(row_2[j+1])$ for each $start_i < j < k$; (iii) $row_2[j] = row_2[j+1]$ for each $k \leq j < start_i + m_i$; (iv) if m' is the exponent of the atom $row_2[k]$, then $m' > rank(row_2[k])$.*

Proof. If $m_i = 1$, by hypothesis we have $rank(A_i) = 0$. Hence, $rank(row_2[start_i + 1]) = 0$, because $row_1 \xrightarrow{=row_\varphi} row_2$, and thus $row_2[start_i + 1]$ is (trivially) reflexive. All claims hold by choosing $k = start_i + 1$.

Let us then assume $m_i > 1$. First, we prove that for each $start_i < j \leq start_i + m_i$, if $row_2[j]$ is reflexive, then for each $j \leq j' \leq start_i + m_i$, $row_2[j'] = row_2[j]$. If $j = start_i + m_i$ there is nothing to prove. Thus, let us consider $j < start_i + m_i$. Since we are assuming that $row_2[j]$ is reflexive, then $\mathcal{O}bs_D(row_2[j]) \subseteq \mathcal{R}eq_D(row_2[j])$. Since $row_1 \xrightarrow{=row_\varphi} row_2$, we have that $\mathcal{R}eq_D(A_i), \mathcal{O}bs_D(A_i) \subseteq \mathcal{R}eq_D(row_2[j])$, and $\mathcal{R}eq_D(row_2[j+1]) = \mathcal{R}eq_D(row_2[j]) \cup \mathcal{O}bs_D(row_2[j]) \cup \mathcal{R}eq_D(A_i) \cup \mathcal{O}bs_D(A_i) = \mathcal{R}eq_D(row_2[j])$. Moreover, again from $row_1 \xrightarrow{=row_\varphi} row_2$, we have that $row_2[j] \cap \mathcal{A P} = row_2[j-1] \cap A_i \cap \mathcal{A P}$ and $row_2[j+1] \cap \mathcal{A P} = row_2[j] \cap A_i \cap \mathcal{A P} = row_2[j-1] \cap A_i \cap \mathcal{A P}$. Thus, $row_2[j+1] = row_2[j]$, because the two atoms feature exactly the same requests and proposition letters (Proposition 4). Then, since $A_i \, row_2[j] \xrightarrow{=D_\varphi} row_2[j+1]$, by iterating the reasoning and exploiting Lemma 12 we can conclude that $row_2[j] = row_2[j']$ for each $j \leq j' \leq start_i + m_i$.

Now, it can be easily shown that if we have two atoms A and A' such that $A \, D_\varphi \, A'$ and A' is irreflexive, then $rank(A) < rank(A')$, and we have just proved that we cannot interleave reflexive atoms with irreflexive ones "above" the A_i's (all irreflexive atoms must "come before" reflexive ones in the part of row_2 "above" the A_i's). Thus, in the worst possible case, the atoms $row_2[start_i + 1], \ldots, row_2[start_i + rank(A_i)]$ may be irreflexive (as $rank(row_2[start_i + 1]) > \ldots > rank(row_2[start_i + rank(A_i)])$ and $rank(A_i) \geq rank(row_2[start_i + 1])$). Note that these irreflexive atoms may be the "first" $rank(A_i)$ atoms above the A_i's only, and not the

"first" $rank(A_i) + 1$, since any atom with rank equal to 0 is reflexive. We conclude that $row_2[start_i + rank(A_i) + 1]$ must be reflexive. Thus, we can choose $k = start_i + rank(A_i) + 1$. Since by hypothesis $m_i \geq rank(A_i) + 1$, we get that $start_i < k \leq start_i + m_i$.

As for the last claim, we have that $rank(row_2[k]) \leq rank(row_2[start_i + 1]) - (k - start_i - 1) \leq rank(A_i) - (k - start_i - 1)$. Then, the exponent m' of $row_2[k]$ is such that $m' \geq m_i - (rank(A_i) - rank(row_2[k]))$, that is, at least $m_i - (rank(A_i) - rank(row_2[k]))$ atoms labelled by $row_2[k]$ occur in the block $start_i + 1, \ldots, start_i + m_i$ of row_2 (see Figure 3). Since by hypothesis $m_i > rank(A_i)$, then $m_i - rank(A_i) > 0$ and $rank(row_2[k]) < m'$. ◄

Now we introduce an equivalence relation $\sim$ over $\mathcal{R}ows_\varphi$ which is the key ingredient of the proofs showing that both satisfiability and MC for D$|_{\mathcal{H}om}$-formulas are decidable.

▶ **Definition 19.** Given two φ-rows $row_1 = A_0^{m_0} \cdots A_n^{m_n}$ and $row_2 = \hat{A}_0^{\hat{m}_0} \cdots \hat{A}_{\hat{n}}^{\hat{m}_{\hat{n}}}$, we say that they are *equivalent*, written $row_1 \sim row_2$, if (i) $n = \hat{n}$, and (ii) for each $0 \leq i \leq n$, $A_i = \hat{A}_i$, and $m_i = \hat{m}_i$ or both m_i and $\hat{m}_i$ are (strictly) greater than $rank(A_i)$.

Note that if two rows feature the same set of atoms, the lower the rank of an atom A_i, the lower the number of occurrences of A_i both the rows have to feature in order to belong to the same equivalence class. As an example, let row_1 and row_2 be two rows with $row_1 = A_0^{m_0} A_1^{m_1}$, $row_2 = A_0^{\overline{m}_0} A_1^{\overline{m}_1}$, $rank(A_0) = 4$, and $rank(A_1) = 3$. If $m_1 = 4$ and $\overline{m}_1 = 5$ they are both greater than $rank(A_1)$, and hence they do not violate the condition for $row_1 \sim row_2$. On the other hand, if $m_0 = 4$ and $\overline{m}_0 = 5$, we have that m_0 is less than or equal to $rank(A_0)$. Thus, in this case, $row_1 \not\sim row_2$ due to the indexes of A_0. This happens because $rank(A_0)$ is greater than $rank(A_1)$. Two cases in which $row_1 \sim row_2$ are $m_0 = \overline{m}_0$ and $m_0, \overline{m}_0 \geq 5$.

The relation $\sim$ has finite index, which is roughly bounded by the number of all the possible φ-rows $row = A_0^{m_0} \cdots A_n^{m_n}$, with exponents m_i ranging from 1 to $|\varphi|$. Since (i) the number of possible atoms is $2^{|\varphi|}$, (ii) the number of *distinct* atoms in any φ-row is at most $2|\varphi|$, and (iii) the number of possible functions $f : \{1, \ldots, \ell\} \to \{1, \ldots, |\varphi|\}$ is $|\varphi|^\ell$, we have that the number of distinct equivalence classes of $\sim$ is bounded by

$$\sum_{j=1}^{2|\varphi|} (2^{|\varphi|})^j \cdot |\varphi|^j \leq 2^{3|\varphi|^2},$$

which is exponential in the length of the input formula φ. We denote the set of the equivalence classes of $\sim$ over all the possible φ-rows by $\mathcal{R}ows_\varphi^{\sim}$.

Now we extend the relation $=^{row_\varphi}\!\!\Rightarrow$ to equivalence classes of $\sim$ in the following way.

▶ **Definition 20.** Given two φ-row classes $[row_1]_\sim$ and $[row_2]_\sim$, we say that $[row_2]_\sim$ is a successor of $[row_1]_\sim$, written $[row_1]_\sim =^{row_\varphi}\!\!\Rightarrow [row_2]_\sim$, if there exist $row_1' \in [row_1]_\sim$ and $row_2' \in [row_2]_\sim$ such that $row_1' =^{row_\varphi}\!\!\Rightarrow row_2'$.

The following result proves that if some $row_1' \in [row_1]_\sim$ has a successor in $[row_2]_\sim$, then *every* φ-row of $[row_1]_\sim$ has a successor in $[row_2]_\sim$.

▶ **Lemma 21.** *Given two φ-row classes $[row_1]_\sim$ and $[row_2]_\sim$ such that $[row_1]_\sim =^{row_\varphi}\!\!\Rightarrow [row_2]_\sim$, for every $row \in [row_1]_\sim$ there exists $row' \in [row_2]_\sim$ such that $row =^{row_\varphi}\!\!\Rightarrow row'$.*

The proof, omitted for space reasons, begins by considering two φ-rows, row and $\overline{row}$, such that $row \in [row_1]_\sim$, $\overline{row} \in [row_2]_\sim$, and $row =^{row_\varphi}\!\!\Rightarrow \overline{row}$ (such a pair always exists by Definition 20). Then, we consider another φ-row, $row' \neq row$ in $[row_1]_\sim$, and we show (constructively) how to build $\overline{row}' \in [row_2]_\sim$ such that $row' =^{row_\varphi}\!\!\Rightarrow \overline{row}'$. This is sufficient to

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Input: a $D|_{\mathcal{H}om}$-formula φ

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1. Put $M \leftarrow 2^{3|\varphi|^2}$, $step \leftarrow 0$ and $row \leftarrow A$ for some atom $A \in \mathcal{A}_\varphi$ with $\mathcal{R}eq_D(A) = \emptyset$.

2. If there exists $0 \leq i < |row|$ such that $\varphi \in row[i]$, return **satisfiable**.

3. If $step = M - 1$, return **unsatisfiable**.

4. Non-deterministically generate a φ-row row' and check that $row \,{=}^{row_\varphi}{\blacktriangleright}\, row'$.

5. Put $step \leftarrow step + 1$ and $row \leftarrow row'$.

6. Go back to 2.

■ **Figure 4** Non-deterministic procedure deciding the satisfiability of a $D|_{\mathcal{H}om}$-formula φ.

prove the claim: $\overline{row}'$ is built by making use of the facts that $row' \sim row$ and $row \,{=}^{row_\varphi}{\blacktriangleright}\, \overline{row}$, and of the properties stated by Lemma 18.

The following result arranges the equivalence classes $\mathcal{R}ows_\varphi^{\sim}$ in a graph $G_{\varphi\sim}$.

▶ **Definition 22.** Let φ be a $D|_{\mathcal{H}om}$-formula. The $\varphi \sim$*graph* of φ is the graph $G_{\varphi\sim} = (\mathcal{R}ows_\varphi^{\sim}, {=}^{row_\varphi}{\blacktriangleright})$.

The next theorem reduces the problem of satisfiability checking for a $D|_{\mathcal{H}om}$-formula φ over finite linear orders (equivalent, by Proposition 10, to deciding if there is a homogeneous fulfilling compass φ-structure that features φ) to a reachability problem in the $\varphi\sim$graph, allowing us to determine the computational complexity of the former problem.

▶ **Theorem 23.** *Given a $D|_{\mathcal{H}om}$-formula φ, there exists a homogeneous fulfilling compass φ-structure $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$ that features φ iff there exists a path in $G_{\varphi\sim} = (\mathcal{R}ows_\varphi^{\sim}, {=}^{row_\varphi}{\blacktriangleright})$ from some class $[row]_\sim \in \mathcal{R}ows_\varphi^{\sim}$ to some class $[row']_\sim \in \mathcal{R}ows_\varphi^{\sim}$ such that (1) there exists $row_1 \in [row]_\sim$ with $|row_1| = 1$, and (2) there exist $row_2 \in [row']_\sim$ and $0 \leq i < |row_2|$ such that $\varphi \in row_2[i]$.*

Proof. Preliminarily we observe that, in (1), if $|row_1| = 1$, then $\{row_1\} = [row]_\sim$; moreover, in (2), if for $row_2 \in [row']_\sim$ and $0 \leq i < |row_2|$ we have that $\varphi \in row_2[i]$, then for any $row'_2 \in [row']_\sim$, there is $0 \leq i' < |row'_2|$ such that $\varphi \in row'_2[i']$.

($\Rightarrow$) Let us consider a homogeneous fulfilling compass φ-structure $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$ that features φ. By Lemmata 15 and 17, $\mathcal{L}(0,0) \,{=}^{row_\varphi}{\blacktriangleright}\, row_1 \,{=}^{row_\varphi}{\blacktriangleright}\, \cdots \,{=}^{row_\varphi}{\blacktriangleright}\, row_{\max(S)}$. Thus there exist two indexes $0 \leq j \leq \max(S)$ and $0 \leq i < |row_j|$ for which $\varphi \in row_j[i]$. By Definition 20, we get that $[\mathcal{L}(0,0)]_\sim \,{=}^{row_\varphi}{\blacktriangleright}\, [row_1]_\sim \,{=}^{row_\varphi}{\blacktriangleright}\, \cdots \,{=}^{row_\varphi}{\blacktriangleright}\, [row_j]_\sim$ is a path in $G_{\varphi\sim}$; it is immediate to check that it fulfils requirements (1) and (2).

($\Leftarrow$) Let us assume there exists a path $[row_0]_\sim \,{=}^{row_\varphi}{\blacktriangleright}\, \cdots \,{=}^{row_\varphi}{\blacktriangleright}\, [row_m]_\sim$ in $G_{\varphi\sim} = (\mathcal{R}ows_\varphi^{\sim}, {=}^{row_\varphi}{\blacktriangleright})$ for which $|row_0| = 1$ and there exists i such that $\varphi \in row_m[i]$. By applying repeatedly Lemma 21 we get that there exists a sequence $row'_0 \,{=}^{row_\varphi}{\blacktriangleright}\, \cdots \,{=}^{row_\varphi}{\blacktriangleright}\, row'_m$ of φ-rows where $row'_0 = row_0$, for every $0 \leq j \leq m$, $row'_j \in [row_j]_\sim$, and there exists i' such that $\varphi \in row'_m[i']$. We observe that, by Definition 16, $|row'_j| = |row'_{j-1}| + 1$ for $1 \leq j \leq m$ and, since $|row'_0| = 1$, we have $|row'_j| = j + 1$. Let us now define $\mathcal{G} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$ where $S = \{0, \ldots, m\}$ and $\mathcal{L}(x, y) = row'_y[y - x]$ for every $0 \leq x \leq y \leq m$. By Lemma 17, $\mathcal{G}$ is a fulfilling homogeneous compass φ-structure. Finally, since $\varphi \in row'_m[i']$, $\mathcal{G}$ features φ. ◀

The size of $G_{\varphi\sim} = (\mathcal{R}ows_\varphi^{\sim}, {=}^{row_\varphi}{\blacktriangleright})$ is bounded by $|\mathcal{R}ows_\varphi^{\sim}|^2$, which is exponential in $|\varphi|$. However, it is possible to (non-deterministically) perform a reachability in $G_{\varphi\sim}$ by using space *logarithmic* in $|\mathcal{R}ows_\varphi^{\sim}|^2$. The *non-deterministic* procedure of Figure 4 exploits this fact in order to decide the satisfiability of a $D|_{\mathcal{H}om}$-formula φ, by using only a working space

polynomial in $|\varphi|$: it searches for a suitable path in $G_{\varphi\sim}$, $[row_0]_\sim \overset{=row_\varphi}{\longrightarrow} \cdots \overset{=row_\varphi}{\longrightarrow} [row_m]_\sim$, where $row_0 = A$ for $A \in \mathcal{A}_\varphi$ with $\mathcal{R}eq_D(A) = \emptyset$, $m < M$, and $\varphi \in row_m[i]$ for $0 \le i < |row_m|$. At the j-th iteration of line 4., row_j is non-deterministically generated, and it is checked whether $row_{j-1} \overset{=row_\varphi}{\longrightarrow} row_j$. The procedure terminates after at most M iterations, where M is the maximum possible length of a simple path in $G_{\varphi\sim}$.

The working space used by the procedure is polynomial: M and *step* (which ranges in $[0, M-1]$) can be encoded in binary with $\lceil \log_2 M \rceil + 1 = O(|\varphi|^2)$ bits. At each step, we need to keep track of two φ-rows at a time, the current one, row, and its successor, row': each φ-row can be represented as a sequence of at most $2|\varphi|$ (distinct) atoms, each one with an exponent that, by construction, cannot exceed M. Moreover, each φ-atom A can be represented using exactly $|\varphi|$ bits (for each $\psi \in \mathrm{CL}(\varphi)$, we set a bit to 1 if $\psi \in A$, and to 0 if $\neg\psi \in A$). Hence a φ-row can be encoded using $2|\varphi| \cdot (|\varphi| + \lceil \log_2 M \rceil + 1) = O(|\varphi|^3)$ bits. Finally, the condition $row \overset{=row_\varphi}{\longrightarrow} row'$ can be checked by $O(|\varphi|^2)$ bits of space once we have guessed row'. This analysis entails the following result (we recall that **NPSPACE** = **PSPACE**).

▶ **Theorem 24.** *The satisfiability problem for* $\mathrm{D}|_{\mathcal{H}om}$*-formulas over finite linear orders is in* **PSPACE**.

We now outline which are the modifications to the previous concepts needed for proving the decidability of satisfiability for $\mathrm{D}|_{\mathcal{H}om}$ with the strict relation $\sqsubset$, in place of $\sqsubseteq$. It is sufficient to replace the definitions of $\overset{=D_\varphi}{\longrightarrow}$, φ-*row* and $\overset{=row_\varphi}{\longrightarrow}$ with the following ones. For the sake of simplicity, we introduce a dummy atom $\boxdot$, for which we assume $\mathcal{R}eq_D(\boxdot) = \mathcal{O}bs_D(\boxdot) = \emptyset$.

▶ **Definition 25.** Given $A_1, A_3, A_4 \in \mathcal{A}_\varphi$ and $A_2 \in \mathcal{A}_\varphi \cup \{\boxdot\}$, we say that A_4 is $D_\varphi \sqsubset$-generated by A_1, A_2, A_3, written $A_1, A_2, A_3 \overset{=D_\varphi \sqsubset}{\Longrightarrow} A_4$ iff (i) $A_4 \cap \mathcal{AP} = A_1 \cap A_3 \cap \mathcal{AP}$ and (ii) $\mathcal{R}eq_D(A_4) = \mathcal{R}eq_D(A_1) \cup \mathcal{R}eq_D(A_3) \cup \mathcal{O}bs_D(A_2)$.

The idea of this definition is that, if an interval $[x, y]$, with $x < y$, is labeled by A_4, and the three subintervals $[x, y-1]$, $[x+1, y-1]$, and $[x+1, y]$ by A_1, A_2, A_3, resp., we want $A_1, A_2, A_3 \overset{=D_\varphi \sqsubset}{\Longrightarrow} A_4$. In particular, if $x = y - 1$, then $A_2 = \boxdot$ (because $[x+1, y-1]$ is not a valid interval). Note that only $[x+1, y-1] \sqsubset [x, y]$, hence we want $\mathcal{O}bs_D(A_2) \subseteq \mathcal{R}eq_D(A_4)$; moreover, since the requests of A_1 and A_3 are fulfilled by a strict subinterval of $[x, y]$, it must be $\mathcal{R}eq_D(A_1) \subseteq \mathcal{R}eq_D(A_4)$ and $\mathcal{R}eq_D(A_3) \subseteq \mathcal{R}eq_D(A_4)$.

▶ **Definition 26.** A φ-$\sqsubset$-row is a finite sequence of φ-atoms $row = A_0^{m_0} \cdots A_n^{m_n}$ such that for every $0 \le i \le n$ we have $m_i > 0$, and for every $0 \le j < i$, $\mathcal{R}eq_D(A_j) \subseteq \mathcal{R}eq_D(A_i)$, $A_i \ne A_j$, and $(A_j \cap \mathcal{AP}) \supseteq (A_i \cap \mathcal{AP})$. Moreover $\mathcal{R}eq_D(A_0) = \emptyset$.

▶ **Definition 27.** Given two φ-rows row and row', we say that row' is a successor of row, denoted as $row \overset{=row_\varphi \sqsubset}{\Longrightarrow} row'$, if $|row'| = |row| + 1$, and for every $0 \le i < |row|$, $row[i] row[i-1] row'[i] \overset{=D_\varphi \sqsubset}{\Longrightarrow} row'[i+1]$, where we assume $row[i-1] = \boxdot$ if $i = 0$.

We conclude the section by stating the **PSPACE**-completeness of satisfiability for $\mathrm{D}|_{\mathcal{H}om}$ over finite linear orders (under both the *strict* and the *proper* semantic variants). The hardness proof can be found in [3].

▶ **Theorem 28.** *The satisfiability problem for* $\mathrm{D}|_{\mathcal{H}om}$*-formulas over finite linear orders is* **PSPACE**-*complete.*

4   Model checking for $\mathrm{D}|_{\mathcal{H}om}$ over Kripke structures

In this section we focus our attention on the *model checking (MC)* problem for $\mathrm{D}|_{\mathcal{H}om}$, namely, the problem of checking whether some behavioural properties, expressed as $\mathrm{D}|_{\mathcal{H}om}$-formulas,

Figure 5 Kripke structure $\mathcal{K}_2$.

are satisfied by a model of a given system. The typical models are *Kripke structures*, which will now be introduced along with the semantic definition of $\mathrm{D}|_{\mathcal{H}om}$ over them.

▶ **Definition 29.** A *finite Kripke structure* is a tuple $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$, where $\mathcal{AP}$ is a finite set of proposition letters, W is a finite set of states, $E \subseteq W \times W$ is a left-total relation between states, $\mu : W \to 2^{\mathcal{AP}}$ is a total labelling function, and $s_0 \in W$ is the initial state.

For all $s \in W$, $\mu(s)$ is the set of proposition letters that hold on s, while E is the transition relation that describes the evolution of the system over time.

Figure 5 depicts the finite Kripke structure $\mathcal{K}_2 = (\{p, q\}, \{s_0, s_1\}, E, \mu, s_0)$, with $E = \{(s_0, s_0), (s_0, s_1), (s_1, s_0), (s_1, s_1)\}$, $\mu(s_0) = \{p\}$, and $\mu(s_1) = \{q\}$. The initial state s_0 is identified by a double circle.

▶ **Definition 30.** A *trace* ρ of a finite Kripke structure $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$ is a finite sequence of states $s_1 \cdots s_n$, with $n \geq 1$, such that $(s_i, s_{i+1}) \in E$ for $i = 1, \ldots, n - 1$.

For any trace $\rho = s_1 \cdots s_n$, we define: (i) $|\rho| = n$, and for $0 \leq i \leq |\rho| - 1$, $\rho(i) = s_{i+1}$; (ii) $\rho(i, j) = s_{i+1} \cdots s_{j+1}$, for $0 \leq i \leq j \leq |\rho| - 1$, is the subtrace of ρ bounded by i and j. Finally, if the first state of ρ is s_0 (the initial state of $\mathcal{K}$), ρ is called an *initial trace*.

▶ **Definition 31.** The interval model $\mathbf{M}_\rho = \langle \mathbb{I}(\mathbb{S}), \circ, \mathcal{V} \rangle$ *induced by a trace* ρ of a finite Kripke structure $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$ is the homogeneous interval model such that: (i) $S = \{0, \ldots, |\rho| - 1\}$, and (ii) for all $x \in S$ and $p \in \mathcal{AP}$: $[x, x] \in \mathcal{V}(p)$ iff $p \in \mu(\rho(x))$.

▶ **Definition 32.** Let $\mathcal{K}$ be a finite Kripke structure and ψ be a $\mathrm{D}|_{\mathcal{H}om}$-formula. We say that a trace $\rho(i, j)$ of $\mathcal{K}$ satisfies ψ, denoted as $\mathcal{K}, \rho(i, j) \models \psi$, iff $\mathbf{M}_\rho, [i, j] \models \psi$. Moreover, we say that $\mathcal{K}$ models ψ, written $\mathcal{K} \models \psi$, iff for all *initial* traces ρ' of $\mathcal{K}$, it holds that $\mathcal{K}, \rho' \models \psi$. The *MC problem* for $\mathrm{D}|_{\mathcal{H}om}$ over finite Kripke structures is the problem of deciding if $\mathcal{K} \models \psi$.

Note that $p \in \mathcal{AP}$ holds over $\rho = s_1 \cdots s_n$ iff it holds over all the states $s_1, \ldots, s_n$ of ρ (*homogeneity assumption*). Since the number of initial traces of $\mathcal{K}$ is infinite, MC for $\mathrm{D}|_{\mathcal{H}om}$ over Kripke structures is not trivially decidable. We now describe how, with a slight modification of the previous satisfiability procedure, it is possible to derive a MC algorithm for $\mathrm{D}|_{\mathcal{H}om}$-formulas φ over finite Kripke structures $\mathcal{K}$. The idea is to consider some finite linear orders – not all the possible ones, unlike the case of satisfiability – precisely those corresponding to (some) initial traces of $\mathcal{K}$, checking whether $\neg\varphi$ holds over them: in such a case we have found a counterexample, and we can conclude that $\mathcal{K} \not\models \varphi$. To ensure this kind of "satisfiability driven by the traces of $\mathcal{K}$", we make a product between $\mathcal{K}$ and the previous graph $G_{\varphi\sim}$, getting what we call a "$(\varphi \sim \mathcal{K})$-*graph*". In the following, we will also exploit the notion of "compass structure *induced by a trace* ρ of $\mathcal{K}$", which is a fulfilling homogeneous compass φ-structure built from ρ and completely determined by it.

Given a finite Kripke structure $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$ and a $\mathrm{D}|_{\mathcal{H}om}$-formula φ, we consider the $(\varphi \sim \mathcal{K})$-graph $G_{\varphi\sim\mathcal{K}}$, which is basically the product of $\mathcal{K}$ and $G_{\varphi\sim} = (\mathcal{R}ows_\varphi^\sim, {}^{=row_\varphi}\!\!\rightarrow)$, formally defined as: $G_{\varphi\sim\mathcal{K}} = (\Gamma, \Xi)$, where:

- Γ is the maximal subset of $W \times \mathcal{R}ows_\varphi^\sim$ s.t.: if $(s, [row]_\sim) \in \Gamma$ then $\mu(s) = row[0] \cap \mathcal{AP}$;
- $\big((s_1, [row_1]_\sim), (s_2, [row_2]_\sim)\big) \in \Xi$ iff (i) $\big((s_1, [row_1]_\sim), (s_2, [row_2]_\sim)\big) \in \Gamma^2$, (ii) $(s_1, s_2) \in E$, and (iii) $[row_1]_\sim {}^{=row_\varphi}\!\!\rightarrow [row_2]_\sim$.

Input: a Kripke structure $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$, a $\mathrm{D}|_{\mathcal{H}om}$-formula φ

1. Put $M \leftarrow |W| \cdot 2^{3|\varphi|^2}$, $step \leftarrow 0$ and $(s, row) \leftarrow (s_0, A)$ for some atom $A \in \mathcal{A}_\varphi$ with $\mathcal{R}eq_D(A) = \emptyset$ and $A \cap \mathcal{AP} = \mu(s_0)$.

2. If $\varphi \notin row[|row| - 1]$, return **yes**.

3. If $step = M - 1$, return **no**.

4. Non-deterministically choose s' such that $(s, s') \in E$.

5. Non-det. generate a φ-row row' and check that $row'[0] \cap \mathcal{AP} = \mu(s')$ and $row \overset{=row_\varphi}{\Longrightarrow} row'$.

6. Put $step \leftarrow step + 1$ and $(s, row) \leftarrow (s', row')$.

7. Go back to 2.

■ **Figure 6** Non-deterministic procedure deciding the existence of initial traces ρ such that $\mathcal{K}, \rho \not\models \varphi$.

Note that the definition of Γ is well-given, since for all $row' \in [row]_\sim$, $row'[0] = row[0]$. The size of $G_{\varphi \sim \mathcal{K}}$ is bounded by $(|W| \cdot |\mathcal{R}ows_\varphi^\sim|)^2$.

Given a generic trace ρ of $\mathcal{K}$, we define the compass φ-structure *induced by ρ* as the fulfilling homogeneous compass φ-structure $\mathcal{G}_{(\mathcal{K}, \rho)} = (\mathbb{P}_\mathbb{S}, \mathcal{L})$, where $S = \{0, \ldots, |\rho| - 1\}$, and for $0 \le x < |\rho|$, $\mathcal{L}(x, x) \cap \mathcal{AP} = \mu(\rho(x))$ and $\mathcal{R}eq_D(\mathcal{L}(x, x)) = \emptyset$. Note that, given ρ, $\mathcal{G}_{(\mathcal{K}, \rho)}$ always exists and is unique: all φ-atoms $\mathcal{L}(x, x)$ "on the diagonal" are determined by the labeling of $\rho(x)$ (and by the absence of requests). Moreover, by Lemma 17, all the other atoms $\mathcal{L}(x, y)$, for $0 \le x < y < |\rho|$, are determined by the $\overset{=row_\varphi}{\Longrightarrow}$ relation between φ-rows.

The following property can easily be proved by induction.

▶ **Proposition 33.** *Given a Kripke structure $\mathcal{K}$, a trace ρ of $\mathcal{K}$, and a $\mathrm{D}|_{\mathcal{H}om}$-formula φ, for all $0 \le x \le y < |\rho|$ and for all subformulas ψ of φ: $\mathcal{K}, \rho(x, y) \models \psi$ iff $\psi \in \mathcal{L}(x, y)$ in $\mathcal{G}_{(\mathcal{K}, \rho)}$.*

We can now introduce Theorem 34, that can be regarded as a version of Theorem 23 for MC.

▶ **Theorem 34.** *Given a Kripke structure $\mathcal{K} = (\mathcal{AP}, W, E, \mu, s_0)$ and a $\mathrm{D}|_{\mathcal{H}om}$-formula φ, there exists an initial trace ρ of $\mathcal{K}$ such that $\mathcal{K}, \rho \models \varphi$ iff there exists a path in $G_{\varphi \sim \mathcal{K}} = (\Gamma, \Xi)$ from some node $(s_0, [row]_\sim) \in \Gamma$ to some node $(s, [row']_\sim) \in \Gamma$ such that: (1) there is $row_1 \in [row]_\sim$ with $|row_1| = 1$, and (2) there is $row_2 \in [row']_\sim$ with $\varphi \in row_2[|row_2| - 1]$.*

Now, analogously to the case of satisfiability, we can perform a reachability in $G_{\varphi \sim \mathcal{K}}$, exploiting the previous theorem to decide whether there is an initial trace ρ of $\mathcal{K}$ such that $\mathcal{K}, \rho \models \neg\varphi$, for a $\mathrm{D}|_{\mathcal{H}om}$-formula φ (i.e., the complementary problem of MC $\mathcal{K} \models \varphi$). The *non-deterministic* procedure of Figure 6 searches for a suitable path in $G_{\varphi \sim \mathcal{K}}$, $(s_0, [row_0]_\sim) \overset{\Xi}{\to} \cdots \overset{\Xi}{\to} (s_m, [row_m]_\sim)$, where $row_0 = A \in \mathcal{A}_\varphi$ with $\mathcal{R}eq_D(A) = \emptyset$, $A \cap \mathcal{AP} = \mu(s_0)$, $m < M$, and $\neg\varphi \in row_m[|row_m| - 1]$ (i.e., $\varphi \notin row_m[|row_m| - 1]$). At the j-th iteration of lines 4./5., $(s_{j-1}, s_j) \in E$ is selected, and row_j is non-deterministically generated checking that $row_j[0] \cap \mathcal{AP} = \mu(s_j)$ and $row_{j-1} \overset{=row_\varphi}{\Longrightarrow} row_j$.

Basically, the same observations about the working space of the procedure in Figure 4 can be done also for this algorithm, except for the space used to encode in binary $M \le |W| \cdot 2^{3|\varphi|^2}$ and $step$, ranging in $[0, M - 1]$, which is $O(\log |W| + |\varphi|^2)$ bits. Moreover we need to store two states, s and s' of $\mathcal{K}$, that need $O(\log |W|)$ bits to be represented.

▶ **Theorem 35.** *The MC problem for $\mathrm{D}|_{\mathcal{H}om}$-formulas over finite Kripke structures is* **PSPACE**-*complete. Moreover, for constant-length formulas, it is* **NLOGSPACE**-*complete.*

Proof. Membership is immediate by the previous space analysis, and the fact that the complexity classes **NPSPACE** = **PSPACE** and **NLOGSPACE** are closed under complement.

As for the **PSPACE**-hardness, we make a reduction from the **PSPACE**-complete *problem of universality* of the language of an NFA [8]. The full proof can be found in [3]. For the **NLOGSPACE**-hardness, there exists a trivial reduction from the *problem of (non-)reachability* of two nodes in a directed graph. ◀

Finally, it is possible to adapt the procedure also for *strict* $D|_{\mathcal{H}om}$ (by exploiting Definitions 25–27).

5 Conclusions

In this paper, we have shown that both satisfiability and model checking for the logic D of sub-intervals – over finite linear orders and finite Kripke structures, respectively – are **PSPACE**-complete, under the homogeneity assumption. We are investigating the possibility of generalizing the given procedures to cope with the logic BE: nothing is known about its satisfiability, while a large gap separates known upper and lower bounds for model checking.

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